$H(t)|\psi(t)\rangle = i\hbar\frac{\partial}{\partial t}|\psi(t)\rangle$ Quantum Lie algebras and Dissipation



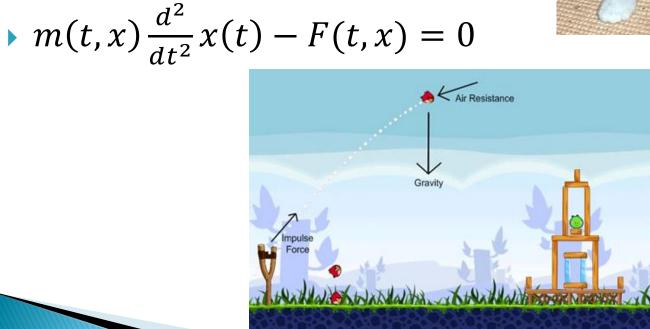
Classical mechanics

F(t,x) = m(t,x)a(t)

 $\rightarrow x(t)$

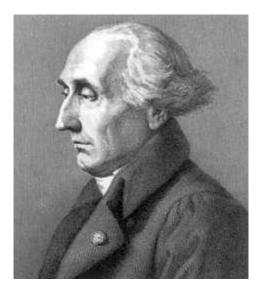
 $\bullet a = \frac{d^2}{dt^2} x(t)$





Fancy!

- $T = Kinetic \ energy$
- V = Potential energy
- L = T V $\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}} \right) = \frac{\partial L}{\partial x} \quad Lagrangian$

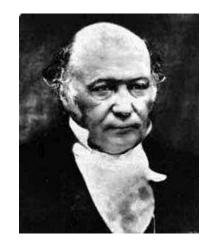


$$H = T + V$$

$$\frac{dp}{dt} = -\frac{\partial H}{\partial x}$$

$$\frac{dx}{dt} = -\frac{\partial H}{\partial p}$$

Hamiltonian



Quantum mechanics

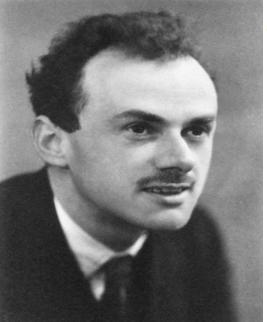
- ▶ x(t)??
- NO!!!!!!!
- $|\psi(t)\rangle$ Kets!



|ψ(t)⟩ = α(t)|Dead⟩ + β(t)|Alive⟩
|α(t)|² = Probability of dead kitty.
|β(t)|² = Probability of living kitty.

The time dependent Schrödinger equation.

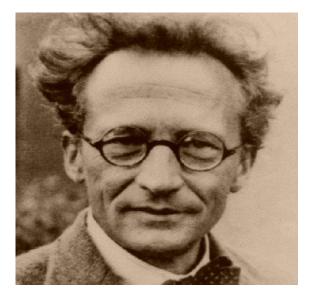
Letting planks constant equal one.



$$i\frac{d}{dt}|\psi(t)\rangle = H(t)|\psi(t)\rangle,$$
$$|\psi(t)\rangle = U(t,t_0)|\psi(t_0)\rangle$$
$$i\frac{d}{dt}U(t,t_0)|\psi(t_0)\rangle = H(t)U(t,t_0)|\psi(t_0)\rangle$$

 $i\frac{d}{dt}U(t,t_0) = H(t)U(t,t_0).$

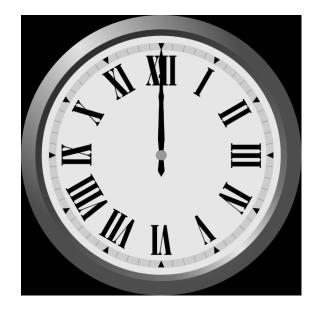
$$i\frac{d}{dt}U(t) = H(t)U(t),$$



Time Development

Case 1: *H* is time independent.

$$U(t) = e^{-iHt}$$



Case 2: *H* is time dependent and commutes with itself at different times. $U(t) = e^{-i \int_0^t H(t) dt}$

Case 3: *H* is time dependent!! Hard problem because operators do not commute in general.

$AB \neq BA$

Lie Algebra method

$$H(t) = \sum_{i=0}^{n} f(t)_{n} A_{n}$$

$$\{A_{1}, A_{2}, \dots, A_{m}\} m > n$$

$$[A,B] = AB - BA$$

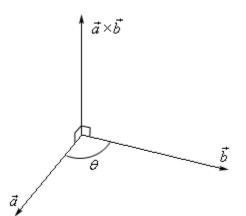
$$i(\frac{d}{dt}U)U^{-1} - H = 0$$

$$U(t) = e^{\alpha_{1}(t)A_{1}} e^{\alpha_{2}(t)A_{2}} \dots e^{\alpha_{n}(t)A_{n}}$$

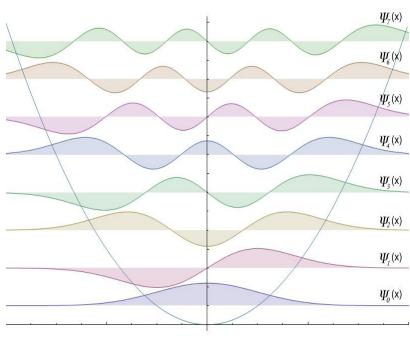
$$\vec{k}$$

$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_{x} & A_{y} & A_{z} \\ B_{x} & B_{y} & B_{z} \end{vmatrix}$$





SHO



$$H = \omega (N + \frac{1}{2}) \qquad \{N, \mathbb{1}\}$$

$$i\dot{U}(t)U(t)^{-1} - H = 0.$$

$$U(t) = e^{\alpha(t)N}e^{\beta(t)\mathbb{1}}$$

$$i\dot{U}U^{-1} = i\dot{\alpha}N + i\dot{\beta}\mathbb{1}$$

$$i\dot{U}U^{-1} - H = (i\dot{\alpha} - \omega)N + (i\dot{\beta} - \frac{1}{2}\omega)\mathbb{1} = 0$$

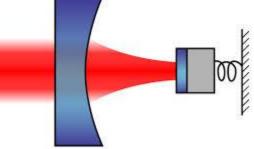
$$i\dot{\alpha} - \omega = \alpha(t) = -i\omega t$$

$$i\dot{\beta} - \frac{1}{2}\omega = \beta(t) = -\frac{i\omega t}{2}$$

$$U = e^{-i\omega tN}e^{-\frac{i\omega t}{2}\mathbb{1}} = e^{-iHt}$$

Optomechanics

 $H = \omega_m b^{\dagger} b + \omega_c a^{\dagger} a - GN + f(t)(b^{\dagger} + b)$ Basis= $[N \ b, b^{\dagger}, b^{\dagger}b, N^2, Nb^{\dagger}, Nb \ 1]$ $U = e^{\alpha N^2} e^{\beta N b} e^{\delta b} e^{\zeta b^{\dagger}} e^{\eta N b^{\dagger}} e^{\xi N} e^{\sigma b^{\dagger} b} e^{\tau \mathbb{1}}$ $i\dot{\alpha} + i\beta\dot{\eta} - i\beta\eta\dot{\sigma} = 0$ $G + i\dot{\beta} + i\beta\dot{\sigma} = 0$ $-f(t) + i\dot{\delta} + i\delta\dot{\sigma} = 0$ $-f(t) + i\dot{\zeta} + i\zeta\dot{\sigma} = 0$ $G + i\dot{\eta} - in\dot{\sigma} = 0$ $-\omega_c + i\beta\dot{\zeta} + i\delta\dot{\eta} + i\dot{\xi} - i\beta\zeta\dot{\sigma} - i\delta\eta\dot{\sigma} = 0$ $-\omega_m + \dot{\sigma} = 0$ $i\delta\dot{\zeta} - i\delta\zeta\dot{\sigma} + i\dot{\tau} = 0$



Recall systems of equations

3x + 2y - 4z = 173x + 3y - 3z = 18-3x + 3y - 4z = 1

Systems of differential equations

$$\begin{split} i\dot{\alpha} + i\beta\dot{\eta} - i\beta\eta\dot{\sigma} &= 0\\ G + i\dot{\beta} + i\beta\dot{\sigma} &= 0\\ -f(t) + i\dot{\delta} + i\delta\dot{\sigma} &= 0\\ -f(t) + i\dot{\zeta} + i\zeta\dot{\sigma} &= 0\\ G + i\dot{\eta} - i\eta\dot{\sigma} &= 0\\ -\omega_c + i\beta\dot{\zeta} + i\delta\dot{\eta} + i\dot{\xi} - i\beta\zeta\dot{\sigma} - i\delta\eta\dot{\sigma} &= 0\\ -\omega_m + \dot{\sigma} &= 0\\ i\delta\dot{\zeta} - i\delta\zeta\dot{\sigma} + i\dot{\tau} &= 0 \end{split}$$



Solution for the time evolution operator of optomechanics

$$\begin{aligned} \alpha &= \frac{G^2(1 - e^{i\omega_m t} + i\omega_m)}{\omega_m^2} \\ \beta &= \frac{-1 + e^{i\omega_m t}}{\omega_m} \\ \delta &= -e^{i\omega_m t} (\int_1^0 -ie^{-i\omega_m t'} f(t') dt' - \int_1^t -ie^{-i\omega_m t'} f(t') dt') \\ \zeta &= -e^{i\omega_m t} (\int_1^0 -ie^{i\omega_m t''''} f(t''') dt'''' - \int_1^t -ie^{i\omega_m t''''} f(t''') dt'''') \\ \eta &= \frac{e - i\omega_m t(-1 + e^{i\omega_m t})G}{\omega_m} \end{aligned}$$

$$\begin{split} \xi &= \frac{1}{\omega_m} (-i\omega_c \omega_m - G \int_1^0 -ie^{-i\omega_m t'} f(t') dt' + \\ &+ e^{i\omega_m} G \int_1^0 -ie^{-i\omega_m t'} f(t') dt' - \omega_m \int_1^0 -\frac{iGf(t'')}{\omega_m} dt'' - \\ &- \omega_m \int_1^0 \frac{ie^{i\omega_m t''} Gf(t'')}{\omega_m} dt'' - \omega_m \int_1^0 -ie^{-i\omega_m t''} G \int_1^{t''} -ie^{-i\omega_m t'} f(t') dk(1) dt'' \\ &+ \omega_m \int_1^t \frac{-1}{\omega_m i} (\omega_c \omega_m + Gf(t'') - e^{i\omega_m t''} Gf(t'') - \\ &- \omega_m e^{i\omega_m t''} G \int_1^0 -ie^{-i\omega_m k(1)} f(t') dt' + \\ &+ \omega_m e^{i\omega_m t''} G \int_1^{t''} -ie^{-i\omega_m k(1)} f(t') dt'' \\ &\sigma = -i\omega_m t \end{split}$$

$$\begin{split} \tau &= -\int_{1}^{0} -e^{i\omega_{m}t'''}f(t''')\int_{1}^{0} -ie^{-i\omega_{m}t'}f(t')dt'dt''' - \\ &- \int_{1}^{0} ie^{i\omega t'''}f(t''')\int_{1}^{t'''} -ie^{-i\omega_{m}t'}f(t')dt'dt''' + \\ &+ \int_{1}^{t} ie^{i\omega_{m}t'''}f(t''')(-\int_{1}^{0} -ie^{-i\omega k(1)}f(t')dt' + \\ &+ \int_{i}^{t'''} -ie^{-i\omega_{m}t'}f(t')dt')dt''' \end{split}$$

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Is this manageable?

$$f(n,m) = m \frac{(n+2)(2n+1)}{2}$$
$$g(n,m) = m(2n+1) + \frac{n^2 + 3n}{2}$$

Not by Hand!



Dissipation in quantum mechanics.

$$H = N + \frac{1}{2}$$

$$H = H_0 \cosh(\frac{\gamma t}{2}) + \frac{1}{2}(a^{\dagger}a)\sinh(\frac{\gamma t}{2})$$

$$\{H_0, (a^{\dagger})^2, a^2\}$$

$$-\frac{1}{2}\sinh(\frac{\gamma t}{2}) + i\dot{\alpha} - 2i\dot{\beta}\alpha + 4i\dot{\delta}\alpha^2 e^{-2\beta} = 0$$

$$i\dot{\delta}e^{-2\beta} - \frac{1}{2}\sinh(\frac{\gamma t}{2}) = 0$$

$$i\dot{\beta} - 4i\dot{\delta}\alpha e^{-2\beta} - \cosh(\frac{\gamma t}{2}) = 0.$$

Aknowlegements

- The NSF for its support and funding.
- The Brigham Young University physics department for the hospitality and giving me the opportunity to work with them.
- My advisors Dr.Jean-Francois Van Huele and Dr. Manuel Berondo.
- > Ty Beaus for his guidance
- The Physics and Mathematics faculty at my home school Cal State San Bernardino.